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| Project ICARUS | |  | | --- | | December 16, 2016 | | 4pm | | W.1.72 | |

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| Meeting called by: | Group | Type of meeting: | Team Meeting |
| Facilitator: | Group | Note taker: | Luke Cattle |
| Timekeeper: | N/A |  |  |

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| Attendees: | Ben Peall, Jonathan Balakumar, Chris Gunn, Josh Crawford, Callum Newman, Luke Cattle |
| Please read: | Last week minutes/actions, Gateway two prep lecture (2:00) |
| Please bring: |  |

## Minutes

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| Agenda item: | Work to be completed for after Christmas | Presenter: | Luke Cattle |

#### Discussion:

We discussed targets for after Christmas and the work we would like done. The main result of this meeting was actions for during the Christmas holidays.

#### Conclusions:

N/A

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| Action items | Person responsible | Deadline |
| * Capability to detect the 3-frequency sound omitted by the black box | Chris | 09/01/17 |
| * Capability to detect the green and red lights in the canyon with the Kinect | Chris/Josh | 09/01/17 |
| * Navigation – Dani to create a grid system which shows potential hazards | Callum | 09/01/17 |
| * Route finding – Dani to calculate optimum route for the tri track on grid system | Callum | 09/01/17 |
| * IMU – To connect the imu up and read inputs from it | Luke | 09/01/17 |
| * Update eportfolio | Josh/Jon | 09/01/17 |
| * Update documents on github | Josh/Jon | 09/01/17 |
| * Image processing with the pi camera | Ben | 09/01/17 |
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## Other Information

#### Observers:

N/A

#### Resources:

N/A

#### Special notes:

N/A